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<input type="checkbox"/>	L1	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4)	6122655

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[◀ Back to Previous Page](#)**A unified optimization approach for a (6+1)-axis robot system***Yilong Chen; You-Liang Gu;*

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